ORIGINAL RESEARCH

Afective autonomous agents for supporting investment decision processes using artifcial somatic reactions

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Abstract

Sometimes, the conscious act of decision-making in humans is dramatically interrupted by situations that warrant an immediate response (e.g. when there is an imminent risk). The human body somatizes this interruption such that an action could be taken without a rational analysis. The above is known as a somatic marker. According to the somatic marker hypothesis, somatic markers could directly infuence several ambits of decision-making. This research work presents the incorporation of artifcial somatic reactions into afective autonomous agents who implement decision-making in the stock market. This implies the design of a general decision architecture for stock markets considering artifcial somatic reactions and the defnition of a set of decision-making algorithms for supporting investment decisions performed by afective autonomous agents (considering artificial somatic reactions). Test scenarios were defined using official data from Standard & Poor's 500 and Dow Jones. The experimental results are promising and indicated that affective autonomous agents are able to experience artificial somatic reactions and achieve effectiveness and efficiency in their decision-making.

Keywords Somatic marker · Artificial somatic reaction · Affective autonomous agent · Investment decision process

1 Introduction

Autonomy is a key factor in the current and future generation of decision-making systems. Progressively, people have delegated a part of their decisions to objects, systems, and environments. An example of the above is the emergence of several proposals for autonomous systems under the concepts of the Internet of Things (Murugaveni and Mahalakshmi [2020;](#page-18-0) Qureshi et al. [2020](#page-19-0); Casadei et al. [2021](#page-18-1); Ravikumar and Kavitha [2021\)](#page-19-1) and Smart City (Belhadi et al. [2020](#page-17-0); Pajuelo-Holguera et al. [2020;](#page-19-2) Zhu et al. [2020](#page-19-3); Dizon and Pranggono [2021\)](#page-18-2). To make decisions autonomously, a system requires certain essential elements, such as baseline data from the decision domain, analysis procedures, evaluation and deliberation criteria, business rules, and performance

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and efectiveness metrics. A relevant aspect of analyzing autonomous systems depends on how they perceive the conditions of their environment, how they react to circumstances and the results of their own decisions, and how they adapt throughout the decision-making process to improve their efficiency and effectiveness.

Meanwhile, another expanding feld that corresponds to afective computing is an area that studies both the recognition, interpretation, and processing of human emotions as well as the design, implementation, and evaluation of the use of artifcial afectivity within systems. In particular, several works have suggested the incorporation of human afectivity and characteristics in artifcial systems (Hou et al. [2021](#page-18-3); Yan et al. [2021](#page-19-4)). Emotions, moods, and even personality profles have been considered. In this sense, a little studied aspect corresponds to the incorporation of somatic markers in artifcial terms within autonomous systems.

Sometimes, the conscious act of decision-making in humans is dramatically interrupted by situations that warrant an immediate response (e.g., when there is an imminent risk). The human body somatizes this interruption, leading to an action that is taken without rational analysis. The above is known as a somatic marker (Damasio [1994](#page-18-4)). According to the somatic marker hypothesis, somatic markers could directly

Considering all the above, the present research work suggests the incorporation of artifcial somatic markers in afective autonomous agents. The main objective is to analyze whether an afective autonomous agent with artificial somatic reactions can improve the effectiveness and efficiency of its decisions. For this, the design of a general decision architecture composed of three layers has been proposed: a somatic layer that is responsible for how the autonomous system reacts to circumstances and the results of its own decisions; an emotional layer that is responsible for the emotional effect that somatic reactions generate on the autonomic system; a decision layer that is responsible for deliberation and fnal decision-making while considering both the technical criteria and the afective criteria. To regulate the magnitude of the system's reactions depending on each stimulus, an artifcial somatic function has been proposed. Likewise, the emotional effects have been defined using emotional regulation functions.

Accordingly, the novelties of the present research are as follows: (1) design of a general decision architecture that considers artifcial somatic reactions in the stock market domain; (2) defnition of a set of decision-making algorithms for supporting investment decisions taken by afective autonomous agents by considering artifcial somatic reactions; (3) defnition of test scenarios for decision-making using official data from Standard & Poor's 500 (Standard & Poor's 500 Index [2021\)](#page-19-5) and Dow Jones (Dow Jones Index [2021](#page-18-6)); (4) analysis of the results by observing the behavior and decisions of afective autonomous agents.

The overall performance of the decision-making process has been measured in terms of the effectiveness of the decision (i.e., the increase in wealth or proftability over time) as well as the efficiency of the decision (i.e., the time required to achieve the aforementioned efectiveness). The use of artificial somatic reactions could partially drive the behavior and the decisions by activating specifc actions or considering specifc rules or knowledge, such as when events that warrant immediate action are perceived (e.g., a substantial economic loss).

The present research extends the knowledge frontier by incorporating a new artifcial somatic marker approach in investment decisions. The design of a somatic layer, an emotional layer, and a decision layer—defned as a unifed architecture that is fexible, specialized, and extensible allow for the layers' potential application in other decision scenarios where complex decision-making is required or in the complex decision-making processes delegated to afective autonomous artifcial systems.

The remainder of this work is organized as follows: the second section includes a literature review; the third section presents the design of artifcial somatic reactions in stock markets in terms of general architecture and a set of algorithms that allow an afective autonomous agent to execute investment decision-making processes in the stock market domain; the fourth section includes the scenario description and experimental results; the ffth section presents a discussion on the results obtained. Finally, the sixth section presents the conclusions derived from the work and recommendations for future work.

2 Literature review

In the last few decades, a signifcant amount of work has been devoted by the research community to the use of rational reasoning in artifcial agent systems (Cabrera and Cubillos [2008](#page-17-1); Cubillos et al. [2010,](#page-18-7) [2013;](#page-18-8) Cabrera-Paniagua et al. [2011;](#page-18-9) Arokiasami et al. [2016](#page-17-2); Mellado Silva et al. [2016](#page-18-10); Acay et al. [2019](#page-17-3); Ehab and Ismail [2020;](#page-18-11) Ismail [2020](#page-18-12); Lv et al. [2020\)](#page-18-13).

Particularly, regarding the use of artificial agents on decision-making systems, several approaches have been proposed to support agent negotiation in a power distribution system for demand reduction (Tom et al. [2020\)](#page-19-6), to apply agents into the e-commerce (Liang et al. [2019;](#page-18-14) Cui et al. [2020\)](#page-18-15), to simulate decision-making processes related to long-distance travel demand (Janzen and Axhausen [2018](#page-18-16)), to implement decision systems based on dynamic argumentation (Ferretti et al. [2017](#page-18-17)), to implement reactive, predictive, and adaptive processes within a virtual entity (Buche et al. [2016\)](#page-17-4), to design a system for order management in heterogeneous production environments (Saha et al. [2016](#page-19-7)), and to design an agent-based model for a multimodal nearfeld tsunami evacuation (Wang et al. [2016](#page-19-8)) among others.

On the other hand, in relation to the inclusion of afectivity in artifcial agent models, some works cover the following: the inclusion of emotional support from a digital assistant in technology-mediated services (Gelbrich et al. [2020\)](#page-18-18); a multi-agent system for guiding users in on-line social environments using sentiment analysis (Aguado et al. [2020](#page-17-5)); simulation of human emotional behavior using intelligent agents (Pudane et al. [2016\)](#page-19-9); simulation of the propagation of information among a group of individuals and its influence on their behavior (Bouanan et al. [2016\)](#page-17-6); definition of an emotional life-cycle for autonomous agents (Jain and Asawa [2016\)](#page-18-19); and design an afective algorithm for purchasing decisions in e-Commerce environments (Cabrera et al. [2015](#page-17-7)) among others. In Kaklauskas et al. ([2020\)](#page-18-20), the afective and biometrical states through a built environment with multisource data were analyzed. Meanwhile, in Sánchez et al. ([2019\)](#page-19-10), an afective framework for a BDI agent was presented. In Rosales et al. ([2019\)](#page-19-11), a framework for the design of artifcial emotion systems was presented. None of the aforementioned cases consider the availability of artifcial somatic reactions within decision-making systems.

Regarding the research line of somatic markers, several works have been devoted to analyze the neuroscience of the sadness (Arias et al. [2020\)](#page-17-8), to analyze mood states and somatic markers (Steenbergen et al. [2020\)](#page-19-12), to explore the relationship between somatic markers and behavior under stress (Huzard et al. [2015\)](#page-18-21), to map the interconnected neural systems underlying motivation and emotion (Cromwell et al. [2020](#page-18-22)), to explore the existence of anticipatory feelings (Stefanova et al. [2020](#page-19-13)), and to analyze the impact of somatic markers in decision-making (Guillaume et al. [2009](#page-18-23); Reimann and Bechara [2010](#page-19-14); Gupta et al. [2011;](#page-18-24) Poppa and Bechara [2018;](#page-19-15) Sandor and Gürvit [2019](#page-19-16)) among others. General or abstract architectures for considering the use of emotions, artifcial somatic markers, and moral aspects have been presented in Chandiok and Chaturvedi ([2018](#page-18-25)), Dyachenko et al. [\(2018\)](#page-18-26), Ichise ([2018\)](#page-18-27), Nagoev et al. ([2018](#page-19-17)), Pessoa ([2019](#page-19-18)), Reia et al. ([2019\)](#page-19-19), Kelley and Twyman ([2020](#page-18-28)), Samsonovich ([2020\)](#page-19-20). It is noteworthy that when considering artifcial somatic markers, the suggestions are general in terms of their use in decision processes and/or in terms of real application domains.

On the other hand, fewer works have explored the implementation of somatic markers within artifcial systems for supporting decision-making processes. In Cominelli et al. ([2015](#page-18-29)), an implementation of somatic markers for social robots was presented. The authors performed a set of tests using the Iowa Gambling Task as the analysis scenario in which the mood was the primary factor responsible for the activation of a somatic reaction. Therefore, the relationship between the triggering cause of a somatic reaction and the agent's judgment, perception, or consciousness level regarding said cause was found weak or non-existent. Furthermore, in Hoogendoorn et al. ([2009](#page-18-30)), a computational decision-making model based on somatic markers was presented. Somatic markers were used as an alarm signal for a particular option and were described in algebraic terms. A non-standard simplifed environment from the domain of a fghter airplane was used as the decision test scenario. Meanwhile, in Cabrera et al. ([2020](#page-17-9)), an abstract framework for implementing artifcial somatic markers within autonomous agent was presented. In order to illustrate the applicability of the framework, a conceptual case study on the transportation of people under a tourism context was presented.

In Hoefinghoff et al. (2012) (2012) , an implementation of a decision-making algorithm based on somatic markers was presented. The agent had a set of S stimuli that could be recognized. The work presented a reduced study case in which the stimuli received were music or *joy pad,* and the possible actions triggered by stimuli were dance, videogames, and a specifc action called *getofmyback*. The robot received rewards by pressing one of the three touch sensors. The robot danced when the music was recognized and talked and moved its arms when the joy pad was recognized. The proposal was extended in Hoefinghoff and Pauli ([2012](#page-18-32)) by the inclusion of a frustration level and an evaluation of using the Iowa Gambling Task test and in Höfinghoff et al. ([2013\)](#page-18-33) in which a software architecture based on Nao robot technology (SoftBanks Robotics [2020](#page-19-21)) was presented.

Considering the available literature, and to the best to our knowledge, compared to the rational approach, minor effort has been devoted to consider the use of an affective dimension within artifcial agent systems devoted to execute autonomous decision-making processes on stock markets (Cabrera-Paniagua et al. [2014](#page-18-34), [2015](#page-18-35); Cabrera et al. [2018,](#page-17-10) [2019](#page-17-11); Cabrera-Paniagua and Rubilar-Torrealba [2021](#page-18-36)). Regarding the use of somatic markers, except the use of the Iowa Gambling Task, non-standard decision environments are usually used for implementing artifcial somatic markers. Therefore, it is not possible to observe the use of artifcial somatic markers within affective autonomous agents as decision-making systems for real-world decision environments (e.g. the stock market domain). Additionally, no works have explored whether the use of artifcial somatic reactions within afective autonomous agents can improve the efectiveness and efficiency of their investment decisions. These aspects that the current research work seeks to explore and verify.

3 Design of artifcial somatic reactions on stock markets

3.1 Human somatic markers

The somatic marker hypothesis proposed by Damasio offered a unified perspective of the body-brain system, explaining that the body serves as the basis for mental representations (Damasio [1994\)](#page-18-4). The body (as a whole) can receive signals when a stimulus (internal or external) triggers it at the brain level. These signals can be translated into a series of body changes: sweating, heart rate increase, muscle twitching (momentary contraction), abdominal pain, paleness, paralysis, and so on. These signals are seen as sudden and immediate physical changes.

Although not entirely clear, a somatic marker could either be an incentive to act or be an inhibitor of action. Similarly, it can have an impact on the recognition of a decision point, generate alternative courses of action, and even give rise to feelings of reward or punishment when a decision is made (Linquist and Bartol [2013](#page-18-5)). People generate memories about events or circumstances and the sensations or reactions experienced at the body level from life experience. Such past feelings or reactions return or become visible in the present

when similar events or circumstances are perceived. In other words, life experience is the means through which somatic markers are incorporated into people.

Somatic marker activation can have both positive and negative valence. An example of positive valence corresponds to experiencing pleasant sensations in the face of a fact or circumstance (e.g. meeting an old friend). On the other hand, an example of negative valence corresponds to experiencing unpleasant sensations in the face of a fact or circumstance (e.g. receiving bad professional or work news). It is noteworthy that in no case is it mandatory that a person must react in a certain way to a stimulus or that two people must react in the same way to the same stimulus. Each person, based on their own experiences, develops and extends their own somatic markers.

3.2 Stock markets

A stock market represents a physical and/or electronic space where investment instruments are traded. According to the specifc objectives of each company, some decide to open up to the stock market through the sale of stocks. A stock represents a very small part of a company, and in addition to granting an idea of ownership over it, it allows its holders the eventual receipt of profts based on its performance in the market. The holders of such stocks are usually identifed as investors. An investor uses capital to acquire investment instruments (including company stocks). An investment portfolio corresponds to a collection of investment instruments associated with a holder, that is, an investor.

The value of a portfolio is based on the performance of the investment instruments constituting it. Considering a portfolio of stocks, its value depends directly on the variation in the price of its stocks. The price variation over time is known as the proftability of the stock. When a positive variation in the price occurs, it is said that there was a positive proftability. On the contrary, when a negative variation in the price occurs, it is said that there was a negative proftability. In the present research work, the calculation of proftability is in accordance with Eq. [1](#page-3-0):

$$
prof_{t} = \frac{SP_{t} - SP_{t-1}}{SP_{t-1}} \cdot 100
$$
\n(1)

where SP_t : stock price in the current period t, SP_{t-1} : stock price in the previous period t−1.

Investment capital can increase over time through (positive) proftability. The successive occurrence of positive proftability allows an accumulation of wealth. In the same manner, the successive occurrence of negative profitability causes a loss of wealth. It is noteworthy that nothing can ensure an investment to consistently offer positive or negative proftability. There is an inherent condition to any

investment that corresponds to the risk. In relation to a stock, risk represents the degree of fuctuation in its price. Similarly, in relation to a portfolio of stocks, risk represents the degree of fuctuation in the price of the stocks constituting it. In the present research work, the risk of a portfolio of stocks is calculated according to Eq. [2:](#page-3-1)

$$
\sigma_P = \sqrt{\sum_{i=1}^N \sum_{j=1}^N w_i w_j \sigma_i \sigma_j C_{ij}},
$$
\n(2)

where σ_i : risk of the ith stock belonging to the portfolio. σ_j : risk of the jth stock belonging to the portfolio. w_i : weight of the ith stock belonging to the portfolio. w_j : weight of the jth stock belonging to the portfolio. C_{ii} : covariance between the ith and jth stocks belonging to the portfolio. N: number of stocks in the portfolio.

3.3 A general decision architecture for stock markets considering artifcial somatic reactions

Figure [1](#page-4-0) shows a general decision architecture for stock markets considering the incorporation of somatic reactions, all the above for affective autonomous agents. At the left end, it is possible to observe the entry of market data and investment results. Meanwhile, at the extreme right, it is possible to observe the output of an investment portfolio. At the center, three layers are identifed: Somatic layer, Emotional layer, and Decision layer.

The somatic layer emulates in artifcial terms the somatic reactions that can be triggered in humans. A set of somatic memories is required which corresponds to long-term memories of associations between objects, events, or past situations and the sensations experienced in each case. In addition, an evaluation mechanism (somatic appraisal) for triggering somatic reactions is necessary if the observed conditions warrant it. This gives rise to somatic rules defned in terms of activation criteria and functions that describe the behavior of a somatic reaction.

The emotional layer is responsible for interpreting somatic reactions and translating them into emotional efects. The present research work considers two pairs of emotions: joy–sadness and trust–fear, following the guidelines of Paul Ekman's basic emotions (Ekman [1982](#page-18-37), [1992](#page-18-38)). An evaluation mechanism (emotional appraisal) that allows updating the emotional state according to the observed conditions is necessary. This gives rise to emotional rules defned in terms of updating criteria and functions that describe the behavior of an emotion.

The decision layer is responsible for analyzing the investment strategy to be followed. For this, it uses both the current emotional state as well as rational investment criteria. The application of investment rules is derived in decisionmaking about the investment portfolio, specifcally, maintaining the current portfolio or applying changes to it.

Fig. 1 General decision architecture for stock markets considering artifcial somatic reactions

3.4 Autonomous decision‑making processes on stock markets

This subsection includes a set of algorithms that allow an afective autonomous agent to make investment decisions in the stock market domain. Algorithm Nº1 represents the general investment decision process. During its execution, there are several calls to other algorithms that will be progressively explained. The algorithm begins by setting the initial investment strategy to use. The current research work considers two diferent investment strategies: a "*risk strategy*", which represents an aggressive investment strategy that seeks greater proftability or wealth and a "*moderate strategy*", which represents an investment strategy that seeks stability and to contain the investment risk. It is noteworthy that according to investment rules and the values of emotional variables, the investment strategy can be modifed during the investment process.

The next step involves the analysis of market data, obtaining a list of candidate portfolios to invest. The next step is to verify the existence of somatic memories. This step seeks to verify the existence of associations between some characteristics of a candidate's portfolio and a somatic reaction. These somatic associations can inhibit the inclusion of a stock within a candidate portfolio (e.g., given its industrial sector) or promote the incorporation of a stock within a candidate portfolio (e.g., given its tendency to rise). Whenever it is required to confgure an investment portfolio, it is mandatory to verify the somatic memories by calling Algorithm No. 2 (that will be explained below), which returns a refned list of candidate portfolios. Considering this refned list and investment strategy, the next step involves setting up an investment portfolio. Then, steps fve, six, and seven indicate that for each investment period, the updated market data is received and the somatic reactions that these market results can generate in the afective autonomous agent are obtained, that is, a somatic appraisal (this requires a call to Algorithm No. 3, which will be explained later). Unlike Algorithm Nº2 in which somatic associations are verifed to confgure an investment portfolio, Algorithm No. 3 seeks to obtain the reactions of the afective autonomous agent from its own investment results. These reactions can be positive ('*Valence*+'), negative ('*Valence −*'), or neutral. These somatic reactions, received as a list from Algorithm No. 3, allow the next step that is the emotional appraisal of the afective autonomous agent through a call to Algorithm No. 4 (which will be explained later). Subsequently, investment rules are applied to determine a decision.

The investment rules correspond to a mixture between technical investment criteria and the state of the emotional variables of the afective autonomous agent. These rules will be discussed in greater depth when explaining the details of Algorithm No. 5. Anyway, at this point, it is important to note that the application of the investment rules within Algorithm No. 5 results in a decision composed of two aspects: a directive with two possible options (to sell or maintain the portfolio) and an investment strategy (concept explained at the beginning of this subsection). In step eleven, the directive is verifed. If the directive corresponds to 'sell', then the portfolio is sold and the investment process goes to step 1, considering the last value of investment strategy. In the case the directive value does not correspond to 'sell', then the afective autonomous agent decides to maintain the current portfolio, going to the next investment period. The Algorithm No. 1 ends when the entire investment period is covered.

On the other hand, Algorithm No. 2 describes the process of verifying somatic memories. The algorithm receives as input parameters a set of somatic memories and a list of candidate portfolios. For each candidate portfolio '*i*' belonging to the list of candidate portfolios and for each stock '*k*' belonging to a specifc candidate portfolio '*i*', the algorithm verifes a set of somatic rules which aim to associate the stock to one of three diferent statuses: 'vetoed', 'promoted', or 'neutral'. If a stock '*i*' belongs to a company and/or an industrial/business sector associated with a 'bad or negative memory', the stock is labeled as 'vetoed'. If a stock '*i*' belongs to a company and/or an industrial/business sector associated with a 'good or positive memory', the stock is labeled as 'promoted'. The algorithm also allows one to promote uptrend or downtrend stocks. If the stock '*i*' is not associated with some somatic rule mentioned above, then its status is set as 'neutral'. The algorithm No. 2 returns a list of refned candidate portfolios in which each stock has one of the three statuses mentioned above.

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Algorithm No. 3 describes the process of somatic appraisal. For each investment period, it is necessary to verify the reactions that are generated in the affective autonomous agent when it knows the updated market data and the variations on own portfolio. Regarding the proftability, a somatic reaction of 'valence+' (positive valence) will be triggered if the somatic function of proftability reaches an upper threshold. Conversely, a somatic reaction of 'valence −' (negative valence) will be triggered if the somatic function of proftability reaches a lower threshold. If both upper and lower thresholds are not reached due to the variation in portfolio proftability, a somatic reaction of 'neutral valence' will be observed (see Fig. [2](#page-8-0)).

Algorithm 3 Somatic Appraisal

Problem description: Activate the somatic evaluation, i.e., obtain the somatic reactions of the affective autonomous agent based on the results of its investment portfolio.

Preconditions: Updated data on the stock market are available.

Postconditions: Based on the variations in profitability and risk of the portfolio, the artificial somatic reactions are registered in the affective autonomous agent.

Input: Portfolio; market data.

Output: Somatic reactions list.

Begin

- 1: **Get** {*profitability*, *risk*} **from** {*portfolio*}
- 2: **If** {*profitability*}>= somatic_upper_threshold_Prof
- 3: somatic_Reaction_Prof = '*Valence +*'
- 4: somatic Reaction Prof Value = '*Value*' (Using Eq. 3)
- 5: **Else If** {*profitability}* <= somatic lower threshold Prof
- 6: somatic_Reaction_Prof = '*Valence -*'
- 7: somatic_Reaction_Prof_Value = '*Value*' (Using Eq. 3)
- 8: **Else**
- 9: somatic_Reaction_Prof = '*Neutral Valence*'
- 10: somatic_Reaction_Prof_Value *= zero*

11: **End If**

- 12: **If** $\{risk\}$ > = somatic upper threshold Risk
- 13: somatic_Reaction_Risk = '*Valence -*'
- 14: somatic_Reaction_Risk_Value = '*Value*' (Using Eq. 4)
- 15: **Else If** $\{risk\} \le$ somatic lower threshold Risk
- 16: somatic_Reaction_Risk = '*Valence +*'
- 17: somatic_Reaction_Risk_Value = '*Value*' (Using Eq. 4)
- 18: **Else**
- 19: somatic_Reaction_Risk = '*Neutral Valence*'
- 20: somatic_Reaction_Risk_Value *= zero*
- 21: **End If**
- 22: **Add**
	- {*somatic*_*Reaction*_*Prof*, *somatic*_*Reaction*_*Prof*_*Value*; *somatic_Reaction_Risk*, *somatic_Reaction_Risk_Value*} **in** {*somatic_reactions_List*}
- 23: return (*somatic_reactions_List)*
- **End Algorithm 3**

The somatic function of proftability is calculated according to Eq. [3.](#page-7-1) SFP describes the magnitude of the artifcial somatic reaction as a function of proftability:

$$
SFP(prof_t) = \frac{2}{1 + e^{-\alpha * prof_t}} - 1 + \gamma
$$
\n(3)

where α corresponds to a sensitivity parameter to profitability and $\alpha \in \mathbb{R}_+$; γ corresponds to a random variable that represents the fuzzy characteristic of the somatic function of proftability and γ : $\mathbb{R} \to \mathbb{R}$; *prof_t* corresponds to the profitability obtained by the portfolio in the period t according to Eq. [\(1](#page-3-0)).

Regarding the risk, a somatic reaction of 'valence+' (positive valence) will be triggered if the somatic function of risk reaches an upper threshold. Conversely, a somatic reaction of 'valence −' (negative valence) will be triggered if the somatic function of risk reaches a lower threshold. If both upper and lower thresholds are not reached due to the variation in portfolio risk, a somatic reaction of 'neutral valence' will be generated (see Fig. [2](#page-8-0)).

On the other hand, the somatic function of risk follows Eq. [4](#page-7-0). SFR describes the magnitude of the artifcial somatic reaction as a function of risk:

$$
SFR(riskt) = \frac{2}{1 + e^{-\varepsilon * (risk_t - \kappa)}} - 1 + \theta
$$
\n(4)

where ε corresponds to a parameter of sensitivity to risk and $\epsilon \in \mathbb{R}_+$; *K* corresponds to a parameter that adjusts the effect of the observed risk and $\kappa \in \mathbb{R}$; θ corresponds to a random variable that represents the fuzzy characteristic of the somatic function of risk, and θ : $\mathbb{R} \to \mathbb{R}$; *Risk*_t corresponds to the volatility measured as the standard deviation of the observed returns multiplied by 100.

The functional structure of Eqs. [\(3\)](#page-7-1) and ([4\)](#page-7-0) makes it possible to model artifcial somatic reactions as a function of proftability and risk, respectively. Through diferent assignments of the parameters, it is possible to confgure the behavior of the affective autonomous agent where a higher value of α (in the case of SFP) and a higher value ϵ (in the case of SFR) implies a high-level sensitivity to stimuli (e.g., high variations in domain indicators), which can cause more recurrent somatic reactions. The role of the κ parameter corresponds to controlling the bias of the affective autonomous agent in the face of perceived risk. The parameter κ allows characterizing the risk aversion of the afective autonomous agent.

Algorithm No. 3 returns a list that contains the somatic reactions derived from the updated portfolio information of proftability and risk in terms of both conceptual reaction and numerical quantifcation of the somatic reaction. In the case of obtaining a somatic neutral reaction, 'neutral valence' is registered as the concept and 'zero' is registered as the numerical quantifcation of the somatic reaction.

For its part, Algorithm No. 4 describes the process of emotional appraisal. This algorithm receives as input parameter a list of somatic reactions (obtained after performing Algorithm Nº3). Considering the somatic reactions, the algorithm makes an emotional appraisal of the afective autonomous agent. If the somatic reaction of profitability has 'valence+' (positive valence) then the joy–sadness emotion takes 'valence+', that is, it turns to joy (using Eq. [5](#page-8-1)). Conversely, if the somatic reaction of proftability has 'valence −' (negative valence) then the joy–sadness emotion

Fig. 2 Somatic reaction function for proftability and risk

It is important to highlight that investment results can generate diferent magnitudes of somatic reactions in the afective autonomous agent which in turn allows the appraisal of its emotional state. If the emotional update reaches some emotional threshold (each emotional threshold is represented by a variable that will be explained later) then the afective autonomous agent can modify its own portfolio. In other words, it is the emotional state that, according to the investment rules (that will be detailed later), can lead the afective autonomous agent to modify its investment portfolio.

$$
JoyS adness(SFPt) = \begin{cases} \frac{2}{1+e^{-\eta s(SFP_t - UTP_{JS})}} - 1 + \phi, & \text{if } SFP_t = \text{Valence } +\\ \frac{2}{1+e^{-\eta s(SFP_t - UTP_{JS})}} - 1 + \phi, & \text{if } SFP_t = \text{Valence } - \end{cases}
$$
(5)

takes 'valence −', that is, it turns to sadness (using Eq. [5\)](#page-8-1). Meanwhile, if the somatic reaction of risk has 'valence+' (positive valence), then the trust–fear emotion takes 'valence+', that is, it turns to trust (using Eq. [6](#page-8-2)). Conversely, if the somatic reaction of risk has 'valence −' (negative valence) then the trust–fear emotion takes 'valence −', that is, it turns to fear (using Eq. [6](#page-8-2)).

The functions to update joy–sadness and trust–fear emotions follow Eqs. [5](#page-8-1) and [6](#page-8-2), respectively. *SFP* corresponds to the somatic reaction value associated with proftability. *SFR* corresponds to the somatic reaction value associated with risk. *UTP* corresponds to an "*Upper Threshold Proftability*"; *LTP* corresponds to a "*Lower Threshold Proftability*".

where η represents a sensitivity parameter to the artificial somatic reaction derived from profitability and $\eta \in \mathbb{R}_+$; ϕ corresponds to a random variable that represents the fuzzy characteristic of the emotional function *JoySadness* and ϕ : $\mathbb{R} \to \mathbb{R}$; *SFP_t* corresponds to the quantification of the artifcial somatic reaction to proftability in the period *t*; *UTPJS* corresponds to the Upper Threshold Proftability, which adjusts by the upper bound the effect of the artificial somatic reaction to profitability, and $UTP_{JS} \in \mathbb{R}$; LTP_{JS} corresponds to the Lower Threshold Proftability, which adjusts by the lower bound the efect of the artifcial somatic reaction to profitability, and $LTP_{JS} \in \mathbb{R}$.

$$
TrustFear(SFRt) = \begin{cases} \frac{2}{1+e^{-\psi s(SFR_t - UTP_{TF})}} - 1 + \varphi, & \text{if} \quad SFP_t = \text{Valence} + \\ \frac{2}{1+e^{-\psi s(SFR_t - UTP_{TF})}} - 1 + \varphi, & \text{if} \quad SFP_t = \text{Valence} - \end{cases}
$$
(6)

where ψ represents a sensitivity parameter to the artificial somatic reaction derived from risk and $\psi \in \mathbb{R}_+$; φ corresponds to a random variable that represents the fuzzy characteristic of the emotional function *TrustFear* and $\varphi : \mathbb{R} \to \mathbb{R}$; SFR_t corresponds to the quantification of the artificial somatic reaction to risk in the period t ; UTP_{TF} corresponds to the Upper Threshold Risk, which adjusts by the upper bound the efect of the artifcial somatic reaction to risk, and $UTP_{TF} \in \mathbb{R}$; LTP_{TF} corresponds to the Lower Threshold Risk, which adjusts by the lower bound the efect of the artificial somatic reaction to risk, and $LTP_{TF} \in \mathbb{R}$.

The functional structure of Eqs. (5) (5) and (6) (6) (6) allows limiting the efects of the emotional pairs joy–sadness and trust–fear, respectively. The foregoing structure seeks to prevent the afective autonomous agent from having extreme episodes in the assessment of emotions. The parameters η (in the case of the *JoySadness* function) and ψ (in the case of the *TrustFear* function) allow controlling the sensitivity level of the afective autonomous agent to SFP and SFR variations. Meanwhile, UTP and LTP parameters controlling the bias in the generation of an artifcial somatic reaction.

The functional form of the proposed Eqs. (3) (3) (3) – (6) (6) is inspired by the logistic functions that are used in the

Algorithm 4 Emotional Appraisal

Problem description: Activate emotional evaluation, i.e., obtain the emotional reactions of the affective autonomous agent from the somatic reactions.

Preconditions: An updated list of artificial somatic reactions is available.

Postconditions: Considering the evaluation of the somatic reactions derived from the profitability and risk of the investment portfolio, the valuation of the emotional pairs joy sadness and trust fear is updated.

Input: Somatic reactions list.

Output: Record of the updated emotional state of the affective autonomous agent.

Begin

```
1: Get {somatic_Reaction_Prof, somatic_Reaction_Risk} from {somatic_reactions_list}
```
- 2: **If** {*somatic_Reaction_Prof*} = '*Valence +*'
- 3: joy_sadness_state = '*Valence +*'
- 4: joy_sadness_value = '*Value*' (Using Eq. 5)
- 5: **Else If** {*somatic_Reaction_Prof}* = '*Valence -*'
- 6: joy_sadness_state = '*Valence -*'

```
7: joy_sadness_value = 'Value' (Using Eq. 5)
```

```
8: Else
```

```
9: joy_sadness_state = 'Neutral Valence'
```
10: joy sadness state = zero

```
11: End If
```

```
12: If {somatic_Reaction_Risk} = 'Valence +'
```
13: trust_fear_state = '*Valence +*'

```
14: trust_fear_value = 'Value' (Using Eq. 6)
```
- 15: **Else If** {*somatic_Reaction_Risk} =* '*Valence -*'
- 16: trust_fear_state = '*Valence -*'

```
17: trust fear value = 'Value' (Using Eq. 6)
```
18: **Else**

```
19: trust_fear_state = 'Neutral Valence'
```
- 20: trust fear value = zero
- 21: **End If**

```
End Algorithm 4
```
statistical literature for the classifcation of events. The form of Eqs. ([3\)](#page-7-1) and ([4](#page-7-0)) corresponds to a family of non-linear functions that allows relating the stimuli associated with proftability and risk to the activation of an artifcial somatic reaction in an afective autonomous agent. This relationship makes it possible to guide the classifcation of events, which corresponds to the variation (or null variation) of the valence of the somatic function in the case of the SFP and SFR functions. Meanwhile, the form of Eqs. (5) (5) and (6) (6) corresponds to a family of non-linear functions that allows relating the activation of an artifcial somatic reaction to its emotional efects. This relationship makes it possible to guide a portfolio change (or its maintenance without major changes, as the case may be).

On the other hand, Algorithm No. 5 describes the application of investment rules. It is important to remember that Algorithm No. 1 receives an investment strategy as the initial parameter, and that as mentioned previously, this parameter represents the frst investment strategy to be used by the afective autonomous agent.

Table 1 Experimental parameters

Parameter	$SC-1$	$SC-2$	$SC-3$
Somatic upper_threshold_Prof	1%	3%	5%
Somatic lower threshold Prof	-1%	$-3%$	$-5%$
Somatic upper_threshold_Risk	0.8%	0.75%	0.70%
Somatic lower_threshold_Risk	0.9%	0.95%	1.0%
Emotional is_upper_threshold	0.075	0.22	0.36
Emotional is_lower_threshold	-0.075	-0.22	-0.36
Emotional tf_upper_threshold	0.24	0.46	0.64
Emotional tf lower threshold	-0.24	-0.46	-0.64

As will be shown later, the affective autonomous agent might modify the said strategy according to the verifcation of a set of investment rules. The investment rules considered in the present research work are the following:

Investment Rule 1: If the joy–sadness emotion reaches or exceeds an upper emotional threshold (i.e., an evident state of "joy"), a "*sell*" directive is triggered, and the investment strategy changes from "*risk strategy*" to "*moderate strategy*" to obtain the profits generated and, simultaneously, to moderate the risk to which the afective autonomous agent is exposed through its portfolio.

Investment Rule 2: If the joy–sadness emotion reaches or exceeds a lower emotional threshold (i.e., an evident state of "sadness"), a "*sell*" directive is triggered, and the investment strategy is maintained as "*risk strategy*" with the aim to increase the proftability or wealth and, simultaneously, to increase the joy of the afective autonomous agent.

Investment Rule 3: If the trust–fear emotion reaches or exceeds an upper emotional threshold (i.e., an evident state of "trust"), a "*sell*" directive is triggered, and considering the level of trust reached by the affective autonomous agent, the investment strategy is maintained as "*risk strategy*".

Investment Rule 4: If the trust–fear emotion reaches or exceeds a lower emotional threshold (i.e., an evident state of "fear"), a "*sell*" directive is triggered, and the invest-

SC	SDEV 2011 (USD)	SDEV 2012 (USD)	SDEV 2013 (USD)	SDEV 2014 (USD)	SDEV 2015 (USD)	SDEV 2016 (USD)	SDEV 2017 (USD)	SDEV 2018 (USD)	SDEV 2019 (USD)
$SC-1$	425	592	631	631	653	680	700	755	784
$SC-2$	182	231	460	462	489	501	504	631	632
$SC-3$	54	54	124	126	311	311	326	354	355

Table 4 Standard deviation on each scenario

Fig. 3 Annual experimental results for the affective autonomous agent

Fig. 4 Risk variation for each scenario

ment strategy changes from "*risk strategy*" to "*moderate strategy*" with the aim to increase the trust level for the afective autonomous agent.

In case any of the emotional thresholds mentioned above are not reached, the investment directive is defined as "*maintain*".

At this point, it is important to remember that somatic reactions derived from both proftability and risk have independent triggering mechanisms (Algorithm No. 3). Subsequently, it was defned that the somatic reaction derived from proftability has an efect on the variation of the joy–sadness emotion as well as on the variation of the trust–fear emotion (Algorithm No. 4). Thus, it is observed that a variation in proftability can trigger a somatic reaction which can infuence the joy–sadness emotion. Similarly, it is observed that a variation in risk can trigger a somatic reaction which can infuence the trust–fear emotion. In any case, the afective autonomous agent makes the decision to sell or maintain its

portfolio considering its emotional state. Somatic reactions infuence the emotional state, and the emotional state infuences the investment decision.

In case the current investment strategy is "*risk strategy*" (aggressive strategy that seeks to increase proftability), the order of verifcation of the investment rules mentioned previously are, frst, rules 1 and 2 (associated with the emotion joy–sadness), subsequently, rules 3 and 4. In case the current investment strategy is "*moderate strategy*" (strategy that seeks to control risk), the order of verifcation of the investment rules are, frst, rules 3 and 4 (associated with the trust–fear emotion), and then, rules 1 and 2.

4 Test scenarios

4.1 General description

Regarding the general market data, the S&P500 index is considered from January 1, 2010 to December 31, 2019

Table 5 Annual proftability variation

SC.	Δ Prof 2011 (%)	Δ Prof 2012 $(\%)$	Δ Prof 2013 $(\%)$	Δ Prof 2014 $(\%)$	Δ Prof 2015 $(\%)$	Δ Prof 2016 $(\%)$	Δ Prof 2017 $(\%)$	Δ Prof 2018 $(\%)$	Δ Prof 2019 $(\%)$
	$SC-1$ 24.47	25.79	18.45	29.65	12.46	3.91	11.58	17.61	4.08
	$SC-2$ 20.11	25.14	17.54	31.12	12.77	3.27	12.35	18.66	3.59
	$SC-3$ 19.00	24.76	15.68	31.97	14.10	3.12	12.01	20.09	3.50

Fig. 5 Annual experimental results for the affective autonomous agent

(Yahoo Finance [2020\)](#page-19-22). Meanwhile, the portfolio composition considers the time series of 30 stocks belonging to the Dow Jones index (Yahoo Finance [2020\)](#page-19-22). The adjusted daily closing value of the stocks is used which considers the adjustment of splits and dividends of fnancial assets. The afective autonomous agent used the data of 2010 to confgure its frst investment portfolio. Thereafter, the experimental scenarios began on the frst trading day of 2011.

Table [1](#page-11-0) shows the parameters used in the test scenarios. It is important to remember that for observing a somatic reaction, it is necessary to reach some threshold (upper or lower). These somatic thresholds are represented by the frst four parameters of the table (identifable by the word "somatic"). Two threshold parameters are defned for a somatic reaction related to proftability (if proftability becomes too high or too low), and two threshold parameters are defned for a somatic reaction related to risk (if risk becomes too high or too low).

Furthermore, investment rules require an emotion to reach some threshold (upper or lower depending on each emotion) for promoting a change in portfolio. These emotional thresholds are represented by the following four parameters in the table (identifable by the word "emotional"). Two threshold

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parameters are defned for an emotional reaction related to joy–sadness: an upper threshold if the emotion tends strongly towards joy and a lower threshold if the emotion tends strongly towards sadness. In addition, two threshold parameters are defned for an emotional reaction related to trust–fear: an upper threshold if the emotion tends strongly towards trust and a lower threshold if the emotion tends strongly towards fear.

Scenario 1 shows parameters with close values between the upper somatic threshold and the lower somatic threshold for a scenario in which the afective autonomous agent is highly sensitive to variations in proftability and risk. When one of the mentioned thresholds is reached, a somatic reaction is expected. Similarly, scenario 1 shows parameters with close values between the upper emotional threshold and the lower emotional threshold for a scenario in which the affective autonomous agent is highly sensitive to its emotional variations. With narrow or close emotional thresholds, the afective autonomous agent is more likely to reach them and thus its emotional valence is defned in a state that motivates a portfolio change. In contrast, scenario 3 shows parameters with more distant values between the upper and lower thresholds (both in the thresholds of somatic reactions and in the emotional thresholds). This makes the afective autonomous agent less sensitive to variations in proftability and risk. Similarly, an accentuated emotional variation is required to reach some emotional threshold, thereby promoting a portfolio change. Therefore, scenario 3 represents an intermediate point between the two scenarios mentioned previously.

In all the scenarios, the afective autonomous agent is considered to start with a "risk strategy". Similarly, by default, in all scenarios, there is a somatic memory that relates "uptrend stocks" to a "good or positive memory" such that the eligibility of this type of stock is promoted whenever a portfolio is configured.

On the other hand, Table [2](#page-11-1) presents the valuation of the stimulus sensitivity parameters. These parameters are meant to establish and delimit the sensitivity of an afective autonomous agent to the variation of the domain indicators. The level of sensitivity of the agent is refected in the intensity of its artifcial somatic reactions.

The parameters $(\alpha, \varepsilon, \eta, \text{ and } \psi)$ play an important role in the activation of artifcial somatic reactions where values close to zero in these parameters are associated with less intense somatic reactions. Conversely, higher values in these parameters are associated with somatic reactions of greater intensity. In the case of the test scenario, it was decided to use values of $\alpha = \epsilon = \eta = \psi = 15$ since this combination of parameters causes around 15% of artifcial somatic reactions in relation to the total of the observed periods.

Meanwhile, it was decided to define the parameter κ = 0.85 whose purpose is that the somatic function associated with risk (SFR) takes a value equal to zero in the expected risk given the information using which this value was determined before initiating the general decision-making process.

The random parameters γ and θ allow one to generate changes in the valence of the somatic function when it is in the vicinity of the upper and lower thresholds as shown in Fig. [2](#page-8-0). In the case of the present test scenario, these random parameters are allowed to have maximum values of 15% of the total spectrum that somatic functions can take. On the other hand, the random parameters φ and φ take values that represent 10% of the total spectrum of the *JoySadness* and *TrustFear* functions.

If the assessment of the somatic function associated with proftability is located in a neighborhood of the limit that activates a somatic reaction and an extreme assessment of *𝛾* is observed, the difference in amplitude with φ prevents the latter from counteracting the efect, triggering, in that case, a change in the *JoySadness* function.

If the assessment of somatic function associated with risk is in a neighborhood of the limit that activates a somatic reaction and an extreme assessment of θ is observed, the difference in amplitude with ϕ prevents the latter from counteracting the efect, triggering, in that case, a change in the *TrustFear* function.

4.2 Experimental results

Table [3](#page-11-2) shows the results for each of the scenarios mentioned above for each investment year from 2011 to 2019. Additionally, the last row (BK) shows the benchmark results of investing on S&P500 index which corresponds to the investment performance that any investor could obtain an investment is directly made following the index. In other words, the BK results were not obtained using the proposal of the current research work, and they are only included to provide an investment referential trajectory.

Each scenario was independently tested 10,000 times, that is, the result of each cell corresponds to an average of 10,000 diferent experimental runs. Table [3](#page-11-2) suggests that consistently over time, the affective autonomous agent shows a better performance in SC-1, followed by SC-2 and SC-3. With an initial investment capital of US10,000 at the beginning of 2011, in SC-1 an accumulated wealth of US\$38,378 was reached at the end of 2019. Meanwhile, for the same initial investment capital, an accumulated wealth of US\$37,261 and US\$37,130, was reached in SC-2 and SC-3, respectively. In SC-1, an average annual proftability of 31.53% was observed. Meanwhile, SC-2 and SC-3 had average annual returns of 30.29% and 30.14%, respectively. Observing the results of Table 3 , it is possible to affirm that overall, the afective autonomous agent has better investment performance than the BK investment strategy.

Figure [3](#page-12-0) is a graphical representation of the behavior over time of the accumulated wealth as an average of the 10,000 independent executions carried out for each scenario. It can be observed that SC-1 (whose parameters are associated with greater recurrence in the activation of artifcial somatic reactions) was consistently higher than the other confgurations. However, despite positive results, the benchmark strategy was far below.

On the other hand, Table [4](#page-12-1) presents the average standard deviation observed for each scenario for all investment periods. Similar to the previous table, it is possible to observe that consistently over time, investments made by the afective autonomous agent generate greater variance in SC-1 followed by SC-2 and SC-3.

Meanwhile, Fig. [4](#page-12-2) shows the risk variation associated with each scenario. It is possible to observe that SC-1 consistently had a higher risk level over time, followed by SC-2 and SC-3. Furthermore, the risk level of the three scenarios showed an upward but not exponential trend over time.

On the other hand, Table [5](#page-12-3) presents the average annual variation in proftability for SC-1, SC-2, and SC-3. It is possible to observe that SC-1 obtains the fve best annual profitability results (years 2011, 2012, 2013, 2016, and 2019), SC-2 obtains the best annual proftability result in 2017, and SC-3 obtains three best annual proftability results (years 2014, 2015, and 2018). In 2011, SC-1 achieves a signifcant annual proftability of 24.47%. Compared to 2011, the results of SC-1 and SC-2 in 2012 are closer to each other. In 2013, the results of annual proftability show a signifcant diference of approximately 3% between SC-1 and SC-3. In the following year 2014, SC-3 obtained a signifcant increase in proftability in relation to SC-1. In 2015, SC-1 once again obtained the highest annual proftability. In 2017, SC-2 obtained the highest annual proftability. In 2018, SC-3 obtained clearly diferent results compared to SC-1. Finally, in 2019, SC-1 obtained the highest annual proftability.

Meanwhile, Fig. [5](#page-13-0) graphically represents the variability and capital behavior for each investment year. The value of the abscissa axis corresponds to the investment year and the ordinate axis corresponds to the accumulated wealth at the end of the investment year. The size of each box represents the data set between the 25th and 75th percentiles of the simulation process. Therefore, the size of each box is representative of the dispersion of the data close to the mean value. Similarly, the outer boundaries of each box correspond to the data variability level both below the 25th percentile and above the 75th percentile.

Figure [5](#page-13-0) graphically summarizes the information provided in Tables [3](#page-11-2) and [4](#page-12-1) according to which considering the mean value of the results, a better performance of the afective autonomous agent is observed in SC-1 compared to SC-2 and SC-3. However, compared to scenarios SC-2 and SC-3, the afective autonomous agent in SC-1 shows a higher level of variability of the results, which evidences a greater exposure to risk of the stocks belonging to the portfolio.

The results of accumulated wealth and risk variation showed that SC-1 obtained the best results with respect to accumulated wealth. However, this scenario steadily showed a higher level of risk. For its part, SC-2 presented betteraccumulated wealth results compared to SC-3. Meanwhile, SC-3 showed the lowest risk levels for all scenarios. The foregoing points indicated that there is no absolute dominance of one scenario confguration over another and suggested the need to seek optimality criteria associated with each affective autonomous agent profile. An adequate investment strategy could require the combination of characteristics of diferent profles within only one. The aforementioned idea can give way to the design of mixed decision-making systems by considering both artifcial somatic markers and personality profles.

5 Discussion

In SC-1, the affective autonomous agent is highly sensitive to variations in proftability and risk. A greater sensitivity has resulted in a greater capacity for adaptation by the affective autonomous agent to the new investment conditions, which ultimately translates into higher returns in the investment process. However, the better returns have as a counterpart a higher level of risk exposure, which can be observed in the greater variability of the results. This is fundamentally based both on the randomness of the prices observed in the stock markets as well as on the randomness of the functions that trigger the somatic reactions in the autonomous agent.

Compared to the results obtained in SC-2 and SC-3, the afective autonomous agent performed better in SC-1, which would suggest that a deep parameter calibration could generate even better results in the investment process. However, it is necessary to consider other types of restrictions that were not considered in the test scenarios, such as the transaction cost (e.g. payment of commissions for each share's purchase/sale operation). Incorporating transaction costs in a test scenario could eventually modify the performance of an afective autonomous agent and, ultimately, the fnal investment results. This implies that an affective autonomous agent could also evaluate the relevance of the change in the portfolio by observing the transaction cost involved.

The results show that the decisions of an afective autonomous agent are efective; these decisions allow the increase of the initial investment capital over time. Furthermore, it is also affirmed that investment based on SC-1 is more efficient as it achieves an increase in the initial investment capital in less time. However, although SC-1 obtains the best annual proftability in most cases, the results are not entirely conclusive given the proximity of some of the annual values obtained. This generates new possibilities for future research works which can correspond to exploring the use of artifcial somatic reactions in autonomous investment processes in greater depth.

The results show that for an investment process, it is better to delegate investment decision-making to an afective autonomous agent than to simply invest after tracking a stock investment index. An afective autonomous agent obtains better results given its ability to feel artifcial somatic reactions, which gives it greater sensitivity to the occurrence and nature of each event in the market. Based on the verification of its somatic memories, the affective autonomous agent can dynamically adapt its investment strategy to the market context.

The use of somatic memories in stock selection was fundamental to the investment process as it guided the investment options of the afective autonomous agent and, therefore, the potential returns that could be obtained during the investment process.

The test scenarios show the need to defne an additional objective function in which the trade-off between the adaptive capacity of the afective autonomous agent and the costs produced by adaptation to the environment is determined, all the derivations obtained from the availability of artifcial somatic reactions and considering a rational–emotional perspective. In other words, the type of autonomy, its range of action, and the mechanisms that sustain this autonomy of decision in an artificial agent offers, on the one hand, a direct beneft to humans who trust and delegate their decisions to artifcial entities. On the other hand, it demands complex designs and implementations that efectively bring decisions closer to how a human might decide in the same context.

The general decision architecture for stock markets with respect to the investment decision-making process can be categorized into three primary layers. First, the somatic layer seeks to detect the reactions generated in the afective autonomous agent during the fuctuations in the stock market. This layer manages memories and somatic rules whose verifcation and evaluation delivers diferent levels of somatic reactions in the agent. The emotional layer receives the somatic reaction from the previous layer and translates it into emotional efects. This is accomplished through the application of emotional rules. Achievable emotional states (joy, sadness, trust, fear) require the emotional update process to reach any of the defned emotional thresholds. The third layer corresponds to the decision layer in which it is verifed whether the current emotional state, along with investment rules, suggests planning regarding the change in the portfolio. At this level, the emotional and rational criteria converge to offer a rational–emotional perspective of the decision.

Separating the investment decision-making process into three layers allows each level to be specialized and decoupled from each other to facilitate the modifcation and extension of each level. The frst layer (somatic) is extensible and allows the incorporation of new mechanisms of somatic appraisal, new types of somatic reactions, and diferent mechanisms of generation, registration, and use of somatic memories without afecting the subsequent layers of the investment decision process. The emotional layer allows the modifcation of the types of emotions, modifying the rules of emotional appraisal as well as the functions of emotional updating without interfering with how somatic reactions are generated or managed (previous layer) and without interfering with how the current emotional state is used in the investment decision (next layer). Finally, the decision layer allows the modifcation or extension of investment rules and investment strategies without altering the work of the previous layers. All this is verifed through the availability of diferent algorithms that refect the general decision architecture in procedural terms.

As indicated in Algorithm Nº5, the autonomy of the afective agent allows it to dynamically modify its investment strategy according to its emotional state and market conditions. This represents a high potential of any decision domain in which complex decision-making can occur or is required to be delegated to artifcial systems. It is possible to adapt the proposal of the present research work to other decision domains for which it would be necessary to modify the somatic layer and the somatic memories (related to the new decision domain) along with the somatic activation criteria. Meanwhile, it would be necessary to replace the set of investment rules and investment strategies based on the new application domain in the decision layer.

On the other hand, the present work has certain limitations. First, a single type of somatic memory was used (i.e., the promotion of "uptrend stocks"). Second, only two rational investment metrics were considered: the variation in proftability and the variation in risk. Third, the use of artifcial somatic reactions was defned only in two senses: the confguration of investment portfolios (by promoting or inhibiting candidate stocks) and the recognition of a decision point, i.e., when the market results generate in the afective autonomous agent a somatic reaction that indicates that "something has happened" and that it is, therefore, necessary to evaluate a potential portfolio change. Fourth, the afective autonomous agent did not incorporate new somatic memories during the general investment decision-making process. The present research work followed an empirical approach based on the implementation of algorithms in R language, leaving the analysis of algorithmic correctness for a future study.

Some key advantages of the current proposal are as follows: a multilayer architectural design, which separates the artifcial somatic reaction from its emotional efect, and consequently, from the final decision made by affective autonomous agents; the existence of parameterizable and adjustable somatic and emotional evaluation functions according to the context; a modular algorithmic design that guides the investment decision-making process in a comprehensive manner.

Additionally, some open challenges of the current proposal are as follows: having afective autonomous agents that are capable of interacting with each other during the decision-making process (whether for cooperation or competition); having afective autonomous agents with the ability to learn by observing the decisions and results obtained by other agents in the domain; extending the current proposal by incorporating personality profles in afective autonomous agents.

6 Conclusion

The present research work suggested the incorporation of artifcial somatic markers in afective autonomous agents. The main objective was to analyze whether an afective autonomous agent with artificial somatic reactions can improve the effectiveness and efficiency of its decisions.

The results of this proposal included the following: the design of a three-layered general decision architecture (somatic layer, emotional layer, and decision layer); an artifcial somatic function to regulate the magnitude of the system's reactions according to each stimulus; emotional update functions based on somatic reactions; a mechanism for deliberation and decision-making; a set of algorithms to guide the decision-making process of afective autonomous agents in the stock market domain.

The test scenarios were defined using official data from Standard & Poor's 500 and Dow Jones. The overall performance of the decision-making process was measured in terms of the efectiveness of the decision (i.e., the increase in wealth or profitability over time) as well as the efficiency of the decision (i.e., the time required to achieve the aforementioned effectiveness). The experimental results were promising and indicated that afective autonomous agents are able to experience artifcial somatic reactions and achieve efectiveness and efficiency in their decision-making.

Regarding the benefts of this research work, frst, it is possible to indicate that the current proposal expanded the frontiers of knowledge on the design of autonomous decision-making systems, particularly through the incorporation of artifcial somatic markers in afective autonomous agents.

Second, the current proposal suggested a novel mechanism for the design and implementation of investment decision support systems, which could potentially be applied to the current electronic investment platforms available in the market as Metatrader (MetaQuotes [2021](#page-18-39)) or xStation (Xtb [2021\)](#page-19-23) whose processes operate in a context of partial autonomy based on permanent human instruction.

Third, the current proposal suggested a decision architecture potentially adaptable to other decision-making scenarios. Its layered structure ensures its fexibility at the design level. Meanwhile, the separation of the general decisionmaking process into diferent algorithms allows its internal structure to be adapted according to the data, domain profles, and business rules.

Future research could extend the number of investment indicators considered in the experimental scenario, for instance, by incorporating the traded volume, the country risk, or indicators of central banks or regulatory entities. Furthermore, a mechanism can be designed to allow an afective autonomous agent to extend its list of somatic memories so that its experience in decision-making represents new knowledge that will potentially be used in future decisions. Finally, a general architecture could be designed to allow the incorporation of artifcial somatic reactions at diferent moments of a decision-making process (e.g., the recognition of a decision point, the identifcation of courses of action, the evaluation of courses of action, the execution of a decision, and so on).

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Data availability The datasets used and analyzed during the current study correspond to S&P500 Index and Dow Jones Index, which are available in [https://fnance.yahoo.com/.](https://finance.yahoo.com/)

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